

MICROCOPY RESOLUTION TEST CHART
NATIONAL BUREAU OF STANDARDS-1963 A



MRC Technical Summary Report #2668

MORSE THEORY FOR SYMMETRIC FUNCTIONALS
ON THE SPHERE AND AN
APPLICATION TO A BIFURCATION PROBLEM

Vieri Benci and Filomena Pacella

AD-A141 709

Mathematics Research Center University of Wisconsin—Madison 610 Walnut Street Madison, Wisconsin 53705

April 1984

(Received January 27, 1984)

DTIC FILE COPY

Sponsored by

U. S. Army Research Office P. O. Box 12211 Research Triangle Park North Carolina 27709 Approved for public release Distribution unlimited



84 05 31 666

UNIVERSITY OF WISCONSIN - MADISON MATHEMATICS RESEARCH CENTER

MORSE THEORY FOR SYMMETRIC FUNCTIONALS ON THE SPHERE AND AN APPLICATION TO A BIFURCATION PROBLEM

Vieri Benci¹ and Filomena Pacella²

Technical Summary Report #2668

April 1984

ABSTRACT

'In this paper we use Conley's index to study the critical points of a functional f on a finite dimensional sphere in presence of a symmetry group.

We prove a theorem which leads to a lower bound on the number of critical points of f when the group is finite, even if the action is not free.

This investigation has been motivated by the following bifurcation problem:

Au = Xu

where A is a variational G-equivariant operator.

We give an estimate on the number of "branches" bifurcating from an eigenvalue of A'(0).

AMS (MOS) Subject Classifications: 35A15, 35B32, 58E05, 57S17.

Key Words: Morse Theory, Group actions, Variational operators, Bifurcation.

Work Unit Number 1 - Applied Analysis.

Dipartimento di Matematica dell'Università di Bari, Bari, ITALY.

Dipartimento di Matematica dell'Università di Napoli, Napoli, ITALY.

Sponsored by the United States Army under Contract No. DAAG29-80-C-0041.

SIGNIFICANCE AND EXPLANATION

We consider the bifurcation problem

 $A(u) = \lambda u$

where A is a nonlinear-variational operator with A(0) = 0. For such operators it is well known that every eigenvalue λ_0 of the linearized operator $A^*(0)$ is a bifurcation point. If the problem exhibits some symmetry, the eigenvalues of $A^*(0)$ are generally degenerate.

Under suitable assumptions, we prove that the number of "branches" which bifurcate from $(0,\lambda_0)$ is larger than or equal to the multiplicity of λ_0 . This very concrete problem leads us to the study of symmetric functionals on the n-dimensional sphere which we analyze using the Conley index.

Acce	ssion For		_	
Unan:	GRA&I TAB mounced ification	*		
By Dist	ribution/] , ,	- C
Ava	lability	Codes	7 (
Dist	Avail or Specia	7		
A-1				

The responsibility for the wording and views expressed in this descriptive summary lies with MRC, and not with the authors of this report.

MORSE THEORY FOR SYMMETRIC FUNCTIONALS ON THE SPHERE AND AN APPLICATION TO A BIFURCATION PROBLEM

Vieri Benci and Filomena Pacella²

INTRODUCTION

We consider the following nonlinear eigenvalue problem

 $A(u) = \lambda u$

where A is an operator of class C^1 defined on a real Hilbert space H such that A(0) = 0.

We suppose that A is variational i.e. there exists a functional J:H+R such that:

A = J'

where J' denotes the gradient of J. It is well known (cf [K], [Bo], [M]) that, under these assumptions, every finite multiplicity isolated eigenvalue of the linearized equation:

 $A^{\dagger}(0)v = \lambda v$

is a bifurcation point of A.

However, if A is odd and λ_0 is an isolated eigenvalue of (0.3) with multiplicity n. Böhme and Marino ({Bo},{M}) have proved that at least 2n "branches" of solutions of (0.1) bifurcate from λ_0 , i.e. the multiplicity of the linearized problem persists in the nonlinear problem (at least in a certain sense).

In this case the functional J is invariant with respect to the action of the group $G_0 = \{ \text{Id}_{\tau} - \text{Id} \} \cong \mathbb{Z}_2.$

Moreover the eigenvalue problem can be reduced, by virtue of the procedure of Böhme and Marino, to the study of the critical points of J on a manifold isomorphic to the

Dipartimento di Matematica dell'Università di Bari, Rari, ITALY.

Dipartimento di Matematica dell'Università di Napoli, Napoli, ITALY.

Sponsored by the United State Army under Contract No. DAAG29-80-C-0041.

(n-1)-dimensional sphere s^{n-1} . The result finally follows from the fact that ${\rm cat}(s^{n-1}/G_n) = n$

where cat(*) denotes the Ljusternik-Schnirelman category.

The purpose of this paper is to investigate if there are other group actions which lead to a multiplicity result of the Böhme-Marino type, even in the case when the L.-S. category of the quotient space is not known and when the action of the group is not free (cf. sect. 1).

In theorem 2.1 we obtain an estimate of the number of critical points of a functional defined on S^{n-1} which is invariant with respect to the action of a finite group. This result allows us to extend the Böhme-Marino result to more general situations (Th. 3.1).

Since in our situation we cannot use the L. S. category, the choice of the Morse theory seems suitable. We have also used the Conley index to treat the degenerate case.

1. Notation and preliminaries

Let M be a n-dimensional compact manifold and f a C^1 function on M. A point x_0 in M is a critical point for f if $f'(x_0) = 0$. Let K be the set of the critical points of f and we suppose that K has a finite number of connected components. The collection of its connected components will be denoted by $\{M_{\pi}\}_{\pi \in \mathbb{R}}$.

Since the sets $M_{\overline{\eta}}$ are isolated in K, using the values of f, we can order them in such a way that they form a Morse decomposition in the sense of [C] and [CZ]. Then to each $M_{\overline{\eta}}$ there corresponds a formal polynomial $p(\cdot,M_{\overline{\eta}})$ which expresses the "Conley's index" of $M_{\overline{\eta}}$ in the gradient flow:

$$(1.2) \qquad \qquad x = -f'(x)$$

For instance, if $f \in C^2$ and $M_{\pi} = \{x_{\pi}\}$, where x_{π} is a nondegenerate critical point, then:

(1.3)
$$p(t,x_{\pm}) = t^{d}$$

where d is the number of negative eigenvalues of the Hessian Hf in the point x_{π} . If $f \in \mathbb{C}^2$ and M_{π} is given by an isolated, degenerate critical point x_{π} , then, in general, $p(t,x_{\pi})$ is not equal to t^d (see [C] for some examples).

We give the following definition:

DEFINITION 1.1 - The number $\mu(M_{\mu}) = p(1,M_{\mu})$ is said to be the multiplicity of M_{μ} .

From our definition it follows that each nondegenerate critical point has multiplicity 1. Definition 1.1 is justified by the following argument. It is known (see also [MP]) that if f is C^2 and has some degenerate critical points, then you can perturb it obtaining another function \tilde{f} , "near" f, which has only nondegenerate critical points. By using the continuity property of Conley's index this implies that if x_0 is an isolated degenerate critical point of f, with $\mu(x_0) = p$, then it splits in at least p nondegenerate critical points of \tilde{f} .

To the manifold M there corresponds a formal polynomial P(t,M), that is the "Poincaré" polynomial of M which "represents" the cohomology of M with coefficients in some field F (see [Sp]). For instance if $M = S^n$, then $P(t,S^n) = 1+t^n$, for each field F, because the cohomology groups of S^n are:

$$H^{i}(S^{n};F) = \begin{cases} F & \text{for } i = 0 \text{ or } n \\ 0 & \text{otherwise} \end{cases}$$

With this understood, the "generalized" Morse relations are:

where $Q_{\mathbf{f}}(\mathbf{t})$ is a polynomial with nonnegative coefficients which depends on f. Because of this we have:

$$(1.5) \qquad \qquad \sum_{\pi} p(t, M_{\pi}) > P(t, M)$$

where this inequality must be interpreted in the sense that every coefficient of the left hand side polynomial is greater than or equal to the corresponding coefficient of P(t,M).

In particular, if f e C2 is nondegenerate we have:

(1.6)
$$\sum_{\pi} p(t, M_{\pi}) = \sum_{i=0}^{m} \alpha_{i} t^{i}$$

where α_i is the number of critical points whose Morse index is equal to i. Then, since the coefficients of P(t,M) are the "Betti" numbers of M, from (1.4) and (1.6) we obtain the classical Morse inequalities for f.

REMARK 1.1 - The definition of Conley's index applies in much more general situations than that described here. The only thing that you require in order to define this index is the presence of a flow in a topological space (see also [SM]).

We end this section recalling something about group actions and introducing some notations (we refer to [Br] for proofs and details).

Let G be a compact Lie-group and X a topological space.

An action of G on X is a map

$$\phi : G \times X + X$$
 , $\phi(g,x) = gx$

with the following properties:

(1.7)
$$1x = x \text{ for each } x \in X, 1 \in G$$

(1.8) $g_1(g_2x) = (g_1g_2)x \quad g_1,g_2 \in G, x \in X$.

A space with an action of a group G is called a G-space. We say that the action of G on X is \underline{free} , if:

(1.9)
$$g \neq 1 = gx \neq x$$
 for each $x \in X$.

We denote by $O_{\mathbf{x}} = \{g\mathbf{x}, geG\}$ the orbit of \mathbf{x} and by \mathbf{X}/G the set of all orbits. When the action is free, each $O_{\mathbf{x}}$ looks like G in the sense that there exists a natural homeomorphism between $O_{\mathbf{x}}$ and G.

The closed subgroup of G defined by

$$G_{\mathbf{x}} = \{g \in G : g\mathbf{x} = \mathbf{x}\}$$

is called the <u>isotrop</u>; group of x. Of course, if the action is free $G_{X} = \{1\}$, for each x.

If $G_X = G$, we say that x is a fixed point under the action of G. We want to point out that if X is a manifold and the action of G is not free, then, in general, X/G is not a manifold.

Given the function f: X + R, we say that f is G-invariant if f(gx) = f(x) for each $x \in X$ and $g \in G$. If X and Y are two G-spaces, we say that a function F: X + Y is G-equivariant if:

F(gx) = gF(x) for each $x \in X$ and $g \in G$.

Finally we recall that, if H is a real Hilbert space, the action of a group G on H is said to be orthogonal if (x,y) = (gx,gy), for every $g \in G$, $x,y \in H$, where (\cdot,\cdot) is the scalar product in H. From now on everytime we say "orthogonal group" it is understood that we are considering a group with an orthogonal action.

2. Critical points of symmetric functions on the sphere.

Let S^n denote the sphere in R^{n+1} , G a finite group acting orthogonally on S^n and let $f: S^n \to R$ be a G-invariant C^1 -function.

We denote by |G| and $|G_X|$ the order of G and G_X respectively and by $|O_X|$ the number of distinct elements of O_X . We set

where K is the set of critical points of f and G.C.D. denotes the greatest common divisor.

REMARK 2.1 - We observe that $|O_x| = \frac{|G|}{|G_x|}$, thus $|O_x|$ is a divisor of |G|. If the action is free, then $\delta = |G|$.

The main result of this section is the following theorem:

THEOREM 2.1: If $\delta > 2$ then f has at least n+1 orbits of critical points provided that each critical point is counted with its multiplicity in the sense of Definition 1.1. Proof: If f has infinitely many critical points then the theorem is proved. So we can suppose that f has only finitely many critical points. This implies that each of them is a connected component in the set K. Hence the sets M_{π} of the Morse decomposition defined in the previous section are just points and the generalized Morse equalities (1.4) are:

(2.2)
$$\sum_{\pi} p(t, M_{\pi}) = P(t, s^{n}) + (1+t)Q_{\underline{f}}(t) .$$

Writing explicitely (2.2) we have:

where $1+t^n$ represents the cohomology of S^n with a field of coefficients F.

Note that the maximum exponent in the left hand side of (2.3) is n because the index-polynomial of each critical point cannot contain a power bigger than t^n , if n is the dimension of the manifold on which f is defined.

Since f is invariant under the action of G the polynomial $p(t, M_{\overline{\eta}})$ is invariant too, i.e. it is the same for points in the same orbit. This implies that each coefficient

 $\alpha_{_4}$ different from 0 is a multiple of $\delta_{_{}}.$ From (2.3) it follows that

(2.4)
$$\begin{cases} \alpha_0 = 1+\beta_0 \\ \alpha_1 = \beta_0+\beta_1 \\ \vdots \\ \alpha_i = \beta_{i-1}+\beta_i \\ \vdots \\ \alpha_n = 1+\beta_{n-1} \end{cases}.$$

We want to prove that each β_1 is different from 0 and is not a multiple of δ , arguing by induction. For β_0 this is true since α_0 is a multiple of δ .

Now suppose that this is true for β_{i-1} . Then (2.4) implies $\alpha_i \neq 0$ and so $\alpha_i = p\delta$, for some $p \neq 0$. Therefore, since β_{i-1} is not a multiple of δ , β_i is different from 0 and is not a multiple of δ . Having proved that $\beta_i > 0$, for each $0 \leq i \leq n-1$, the assertion follows from (2.4), because each α_i has to be greater than zero.

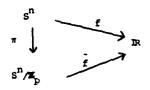
REMARK 2.2 - From the proof of the previous theorem it turns out that since each α_i is different from 0, for every 0 < i < n, f has at least δ critical points whose polynomials contain the power $t^{\frac{1}{2}}$.

COROLLARY 2.1 - If $f \in C^2$ is not degenerate, then there exists at least one orbit of G consisting of critical points of f with Morse index i, for i = 0, ..., n. In particular f has at least n+1 critical points which lie in different orbits.

PROOF: It follows from remark 2.2 and the fact that for each nondegenerate critical point x_{π} , $p(t, \{x_{\pi}\}) = t^{d}$ where d is the Morse index of x_{π} .

COROLLARY 2.2 - If the action of G on Sⁿ is free, then f has at least (n+1)|G| critical points.

REMARK 2.3 - If $G = \mathbb{Z}_p$ and the action is free the assertion of Corollary 2.1 can be obtained using the Ljusternik-Schnirelman category. In fact, consider the diagram



where π is the projection and \widetilde{f} is defined by the diagram itself. Since $\operatorname{cat}(S^n/\mathbb{Z}_p)=n+1$, then \widetilde{f} has at least n+1 critical points. Then f has at least (n+1)|G| critical points. Under this point of view Corollary 2.1 is an extension of this result any finite group G. However the knowledge of $\operatorname{cat}(S^n/G)$ gives extra information in f "degenerate" case. In fact if $\operatorname{cat}(S^n/G)=n+1$, there exist always at least (n+1)|G| distinct critical points, no matter how degenerate they are. If $\operatorname{cat}(S^n/G) \le n$, then using Corollary 2.2, we can conclude that there exists at least (n+1)|G| critical points only if they are counted with their multiplicity in the sense of definition 1.1.

REMARK 2.4 - The result of Theorem 2.1 is of topological nature. Therefore the same result applies not only to the n-dimensional sphere but to any manifold G-homeomorphic to it.

3. A bifurcation theorem.

We begin this section by stating the following Lemma which is the equivariant version of a Lemma of A. Marino [M] (cf. also [Bo]).

LEMMA 3.1 - Let G be a group acting orthogonally on the Hilbert spaces, x_1, x_2 and Y.

Let Ω be a G-invariant neighborhood of 0 in $x_1 \times x_2^{(1)}$ and set $\Gamma = \{(x_1, x_2) \in x_1 \times x_2 : |x_2| \le \gamma |x_1|\}, \gamma > 0. \text{ Let } B : \Gamma \cap \Omega - \{0\} + Y \text{ be a } C^1 \text{-operator}$

with the following properties:

i)
$$\lim_{x_1 \neq 0} \frac{B(x_1, 0)}{|x_1|} = 0$$

ii) there exists an isomorphism B₀ from X₂ to Y such that:

$$B'_{x_2}(x_1,x_2) \rightarrow B_0$$
 strongly if: $|x_2|$

$$|x_1| + |x_2| + 0$$
 and $\frac{|x_2|}{|x_1|} + 0$
iii) $B_{x_1}^{i}(x_1, x_2) + 0$ strongly if $|x_1| + |x_2| + 0$ and $\frac{|x_2|}{|x_1|} + 0$

iv) B is G-equivariant.

For c,6 > 0 set

$$c = \{(x_1, x_2) \in x_1 \times x_2 : |x_2| < c |x_1|\}$$

$$F = \{x_1 \in x_1 : 0 < |x_1| < \delta\}.$$

Then

If c and
$$\delta$$
 are sufficiently small there exists an unique function
$$\phi : F + \Omega$$
with its graph in C such that
$$B(x_1, x_2) = 0 \quad \text{if and only if} \quad x_2 = \phi(x_1)$$

(II) The function
$$\phi$$
 is C^1 and $\lim_{x_1 \to 0} \phi^1(x_1) = 0$

for every (x_1,x_2) e c n Ω .

In $x_1 \times x_2$ there is the "diagonal" action of G: $g(x_1,x_2) = (gx_1,gx_2) \quad g \in G, (x_1,x_2) \in X_1 \times X_2.$

(III) \$ is G-equivariant.

PROOF: The proof of (I) and (II) is contained in [M]. We have only to prove that ϕ is G-equivariant. For every $g \in G$ and $x_1 \in F$, by (I), $\phi(gx_1)$ is the only point such that

(3.1)
$$B(gx_1,\phi(gx_1)) = 0$$
.

But we also have

$$B(gx_4,g\phi(x_4)) = gB(x_4,\phi(x_4)) = 0$$
.

By the above equality and (3.1) it follows that $\phi(gx_1) = g\phi(x_1)$. The proof is complete.

Now let H be a Hilbert space on the real field with the orthogonal action of a group G and let $\Omega\subseteq H$ be a G-invariant open set, with $0\in\Omega$.

We consider the equation:

$$A(u) = \lambda u$$

where A is a variational G-equivariant operator of class C^{1} , i.e. there exists a G-invariant functional of class C^{2} , J: H + R such that

$$A(u) = J'(u)$$

where J' denotes the gradient of J. Moreover, we suppose that $\lambda(0) = 0$ so that 0 provides the trivial solution of (3.2).

Now lets suppose that λ_0 is an isolated eigenvalue of A'(0) of finite multiplicity. By our assumptions A'(0) is a selfadjoint operator, then we have the following splitting of H:

where $H_1 = \ker(A^*(0) - \lambda_0^{-1})$ (I denotes the identity in H) and $H_2 = H_1^L = \operatorname{range}(A^*(0) - \lambda_0^{-1})$. P_1 and P_2 will denote the orthogonal projection on H_1 and H_2 respectively.

For every $u \in H$, u_1 and u_2 will denote P_1u and P_2u respectively.

Since G is an orthogonal group, H_1 and H_2 are invariant under the action of G. Using this decomposition of H, equation (3.2) is equivalent to the following system:

(3.4)
$$\begin{cases} P_{\uparrow} \{Au - \frac{(Au_{\downarrow}u)}{|u|^2} u\} = 0 \\ P_{2} \{Au - \frac{(Au_{\downarrow}u)}{|u|^2} u\} = 0 \end{cases}$$

where | | is the norm in H.

The operator:

$$Bu = B(u_1, u_2) = P_2[Au - \frac{(Au, u)}{|u|^2} u]$$

is G-equivariant. In fact:

$$B(gu_1, gu_2) = P_2[A(gu_1, gu_2) - \frac{(Agu, gu)}{|gu|^2} gu] =$$

$$= P_2[gAu - \frac{(Au_1u)}{|u|^2} gu] = gP_2[Au - \frac{(Au_1u)}{|u|^2} u] .$$

We have used the fact that G is orthogonal and A is G-equivariant. Moreover B satisfies all the hypotheses of Lemma 3.1 (see [M]). Then we deduce the existence of a cone $C = \{u : |P_2u| \le c|P_1u|\}$, a number $\delta > 0$ and a C^1 - G-equivariant function:

such that:

(3.5)
$$\lim_{u_1 \to 0} \phi^*(u_1) = 0$$

(3.6)
$$B(u_1,u_2) = 0$$
 if and only if $u_2 = \phi(u_1)$.

Let us call M the graph of ϕ . This is a G-invariant n-dimensional manifold, where n is the dimension of H_4 .

Then we consider the sphere $S_{\rho} = \{u \in H : |u| = \rho\}$ and prove the following: LEMMA 3.2 - There exists $\rho_0 > 0$, such that, for each $0 < \rho < \rho_0$, $M_{\rho} : S_{\rho} \cap M$ is Ghomeomorphic to the (n-1)-dimensional sphere S_1 in H_1 .

PROOF: For u_1 in S_1 , i.e. $|u_1| = 1$, and ε small enough we consider the map:

$$s_1 \times [0, \epsilon] + R$$

defined by: $g(u_1,t) = \frac{1}{2} |tu_1 + \phi(tu_1)|^2$. We have:

$$\frac{\partial}{\partial t} g(u_1, t) = (tu_1 + \phi(tu_1), u_1 + \phi'(tu_1)u_1) =$$

$$= t(u_1, u_1) + t(u_1, \phi'(tu_1)u_1) + (\phi(tu_1), u_1) +$$

$$+ (\phi(tu_1), \phi'(tu_1)u_1) .$$

Thus by the property of ϕ and ϕ it follows that

$$\frac{\partial}{\partial t} g(u_1,t) = t |u_1|^2 + o(t) .$$

Therefore there exists $\rho_0 > 0$ such that

$$\frac{\partial}{\partial t} g(u_1,t) > 0$$
 for every $t \in (0,\rho_0)$.

Then we can apply the implicit function theorem to solve the equation:

$$g(u,t) = \frac{1}{2} \rho^2 \quad (\text{for } \rho < \rho_0)$$

and we can say that there exists an unique function:

$$\tau : S_1 + (0,\rho_0)$$

with the property that:

$$g(u_1,t) = \frac{1}{2} \rho^2$$
, if and only if $t = \tau(u_1)$.

Note that since g is G-invariant, also τ is G-invariant.

Then we consider the map:

f:
$$S_1 + M_D$$
 defined by:
 $f(u_1) \approx \tau(u_1)u_1 + \phi(\tau(u_1)u_1)$.

This map is the required G-homeomorphism.

It is easy to see that, since τ is G-invariant, and ϕ is G-equivariant, f is G-equivariant. Moreover f is bijective because if $u_1 + \overline{u}_1$, then $\tau(u_1)u_1 + \tau(\overline{u}_1)u_1$, since $\tau(u_1)$ and $\tau(\overline{u}_1)$ are both positive, and this implies that the corresponding points in the graph of ϕ are different.

We now need the following lemma whose proof can be found in [M].

LEMMA 3.3 - Every critical point of $J|_{M_{\tilde{p}}}$ is a critical point of $J|_{S_{\tilde{p}}}$, and this provides a solution of equation (3.2).

Now we can state the main result of this section:

Theorem 3.1 - Let H_1 be the eigenspace of A'(0) corresponding to an isolated eigenvalue λ_0 of finite multiplicity n. Suppose that A is G-equivariant where G is a finite group and set

(3.6')
$$v = G.C.D.\{|o_{ij}|, u \in S_1 \cap H_1\}$$
.

Then if $\nu > 2$, for every ρ small enough, equation (3.2) has at least n orbits of solutions u such that $\|u\|_{H^1} = \rho$, provided that every solution is counted with its multiplicity in the sense of Definition 1.1.

PROOF: By lemma 3.3, it is sufficient to estimate the number of critical points of $J|_{M_{\rho}}$.

By lemma 3.2 we know that M_{ρ} is G-diffeomorphic to $S_1 \cap H_1$ which is a (n-1) dimensional sphere. Therefore theorem 2.2 can be applied (cf. remark 2.4) with

$$\delta = G.C.D.\{|0_{ij}| : u \in K\}$$

with

$$K = \{ u \in M_{\rho} \mid (J|_{M_{\rho}})^{\dagger}(u) = 0 \}$$
.

By the definition of δ ,

and by lemma 3.2

G.C.D.
$$\{|0_{u}| : u \in M_{0}\} = v$$
.

 \Box

Then the conclusion follows.

REMARK 3.2 - Notice that the number 2 defined by (3.6°) depends only on the action of G on the eigenspace H_1 corresponding to the eigenvalue λ_0 (or more precisely on $H_1 \cap S_1$). The action of the group on $H_2 = H_1^{\perp}$ is not relevant to the bifurcation from λ_0 .

As an application of the previous Theorem we will study the following problem:

(3.7)
$$-\Delta u = \mu f(u) , \quad u \in H_0^1(\Omega)$$

where $\Omega\subset \mathbb{R}^2$ is the square $(]-\frac{\pi}{2},\frac{\pi}{2}[]^2$ and $H_0^1(\Omega)$ denotes the usual Sobolev space. Ω is invariant under the action of the group of the symmetry of the square which is denoted by C_{4v} . To be more precise C_{4v} is the group of the following matrices:

$$\mathbf{c}_{4\mathbf{v}} = \{ \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix} \} .$$

The group $C_{\underline{a}\underline{v}}$ induces an action on $H^1_0(\Omega)$ in the following way

$$T_{\alpha}u = u(g(x,y))$$
 , $g \in C_{\underline{A}v}$ $(x,y) \in \Omega$.

We suppose that

(3.8)
$$f \in C^{1}(\mathbb{R})$$

(3.9)
$$f'(t) \le a_1 + a_2 |t|^p pem$$

(3.10)
$$f(0) = 0$$
; $f'(0) = 1$.

We now set $F(t) = \int_0^t f(s)ds$. Then by standard arguments it follows that the functional

$$(3.11) J(u) = \int_{\Omega} F(u) dx dy$$

is a $C^2 - C_{4v}$ -invariant functional on $H_0^1(\Omega)$. On $H_0^1(\Omega)$ we use the gradient norm: $\int_{\Omega} |\nabla u|^2 dx dy$

<-,.> will denote the corresponding scalar product. Then the critical points of J on the sphere $\{\|u\|_{H^{\frac{1}{2}}} = \epsilon\}$ satisfy the following equation

$$\int_{\Omega} f(u)v \, dxdy = \lambda \int_{\Omega} \nabla u \nabla v \, dxdy$$

which gives a solution of (3.7) with $\mu = \frac{1}{\lambda}$.

Now we define the operator A : $H_0^1(\Omega) + H_0^1(\Omega)$ by the formula

$$\langle A(u), v \rangle = \int_{\Omega} f(u)v \, dxdy \text{ for every } v \in H_0^1(\Omega)$$
.

It is known that, by virtue of (3.8), (3.9) and (3.10) A e $c^{1}(H_{0}^{1}(\Omega))$ and

$$\langle A^{\dagger}(0) \{ v \}, w \rangle = \int_{\Omega} f^{\dagger}(0) v w dx dy = \int_{\Omega} v w dx dy$$
.

The eigenvalue problem for A'(0), in weak formulation, takes the form

$$\langle A^{\dagger}(0)[v],w\rangle = \lambda \langle v,w\rangle \quad \forall w \in H_0^{\dagger}(\Omega)$$

which explicitly gives

$$\int_{\Omega} vw \, dxdy = \lambda \int \nabla u \nabla w \, dxdy \qquad \forall \, w \in H_0^1(\Omega)$$

or

Therefore the eigenvalues of A'(0) are given by the formula

$$\lambda_{m,n} = \frac{1}{n^2 + n^2}$$

and the corresponding eigenfunctions are: $\sin n(x + \frac{\pi}{2})\sin m(x + \frac{\pi}{2})$, that is:

sin nx · sin my n,m both even sin nx · cos my n even, m odd (3.13)cos nx . sin my n odd, m even cos nx · cos my n,m both odd .

It is easy to see that in the first three cases $C_{4,v}$ induces an action on the eigenspaces corresponding to $\ \lambda_{mn}$ which does not have fixed points.

Moreover, since $|c_{4,v}| = 8$ it is obvious that

$$\delta : G.C.D.\{c_{4,v}(u)\} u \in H_1 \cap S^1\} > 2$$

if H_1 is an eigenspace of A'(0) (and of $-\Delta$) which does not contain fixed points.

Therefore, by theorem 3.1, the following result follows:

Theorem 3.2 - Let μ be a eigenvalue of - Λ and suppose that $\mu = m^2 + n^2$ implies that m and n are not both odd. Then μ is a bifurcation point of (3.7) and if k is the dimension of the corresponding eigenspace then for every small ϵ , (3.7) has at least

2(k+1) solutions u such that ||u|| H₀¹(Ω)

REFERENCES

- [B] Bott, R., Lectures on Morse theory, old and new, Bull. Amer. Math. Soc. Vol. 7, No. 2, Sept. 1982.
- [Be] Benci, V., A geometrical index for the group S¹ and some applications to the study of periodic solutions of ordinary differential equations, Comm. Pure Appl. Math. (1981).
- [Bo] Böhme, R., Die Lösung der Verzweigungsgleichungen für nichtlineare Eigenwertproblem,
 Math. Z., 127, (1972), 105-126.
- [Br] Bredon, G., Introduction to compact transformations groups, Academic Press (1972).
- [C] Conley, C. C., Isolated invariant sets and the Morse index, CBMS, Regional Conf. Series in Math., 38 (1978).
- [CZ] Conley, C. C. and Zendher, E., Morse type index for flows and periodic solutions for Hamiltonian equations, to appear in Comm. Pure and Appl. Math.
- [FH] Fadell, E. R. and Russeini, S., Relative Cohomological index theories, to appear.
- [FR] Fadell, E. R. and Rabinowitz, P. H., Bifurcation for odd potential operators and an alternative topological index, J. Funct. Anal., 26, 1977, 48-67.
- [FR] Fadell, E. R. and Rabinowitz, Ph. H., Generalized cohomological index theories for Lie Group actions with an application to bifurcations questions for Hamiltonian systems, Inv. Math. 45, (1978), 139-174.
 - [K] Krasnoselski, M. A., Topological Methods in the Theory of Nonlinear Integral Equations, Macmillan, New York, 1964.
 - [M] Marino, A., La biforcazione nel caso variazionale, Conf. Sem. Math. Univ. Bari, 132, (1977).
- [MP] Marino, A. and Prodi, G., Metodi perturbativi nella teoria di Morse, Bollettino
 U.M.I. (4) 11, Suppl. fasc. 3 (1975), 1-32.
- [P] Pacella, F., Central configurations of the N-body problem, MRC Technical Summary Report #2534.
- [Sa] Sattinger, D. F., Group Theoretic Methods in Bifurcation Theory, Lecture Notes, Springer Verlag 1979.

- [Sm] Smoller, J., Shock Waves and Reaction-Diffusion Equations, Springer-Verlag 258 (1983).
- [Sp] Spanier, E., Algebraic Topology, McGraw-Hill Book Co., Inc., New York 1966.

VB/FP/jvs

SECURITY CLASSIFICATION OF THIS PAGE (When Date Entered)

REPORT DOCUMENTATION	PAGE	READ INSTRUCTIONS BEFORE COMPLETING FORM			
T. REPORT NUMBER	2. GOVT ACCESSION NO.	3. RECIPIENT'S CATALOG NUMBER			
#2668	AD-A74=				
4. TITLE (and Subtitio)	,	S. TYPE OF REPORT & PERIOD COVERED			
Morse Theory for Symmetric Function	onals on the	Summary Report - no specific			
Sphere and an Application to a Bif	reporting period				
Problem					
7. AUTHOR(a)	6. CONTRACT OR GRANT NUMBER(*)				
Vieri Benci and Filomena Pacella	DAAG29-80-C-0041				
9. PERFORMING ORGANIZATION NAME AND ADDRESS	10. PROGRAM ELEMENT, PROJECT, TASK AREA & WORK UNIT NUMBERS				
Mathematics Research Center, Univ	Work Unit Number 1 -				
610 Walnut Street	Applied Analysis				
Madison, Wisconsin 53706	12. REPORT DATE				
U. S. Army Research Office		April 1984			
P.O. Box 12211		13. NUMBER OF PAGES			
Research Triangle Park, North Carol	ina 27709	17			
14. MONITORING AGENCY NAME & ADDRESS(If different	from Controlling Office)	15. SECURITY CLASS. (of this report)			
		UNCLASSIFIED			
		154. DECLASSIFICATION/DOWNGRADING SCHEDULE			
16. DISTRIBUTION STATEMENT (of this Report)		L			
Approved for public release; distribution unlimited.					
17. DISTRIBUTION STATEMENT (of the abstract entered in Block 20, If different from Report)					
18. SUPPLEMENTARY NOTES					
19. KEY WORDS (Continue on reverse side if necessary and identify by block number)					
Morse Theory, Group actions, Variational operators, Bifurcation					
-·					
20. ABSTRACT (Continue on reverse side if necessary and identify by block number)					
In this paper we use Conley's index to study the critical points of a					
functional f on a finite dimensional sphere in presence of a symmetry group.					
We prove a theorem which leads to a lower bound on the number of critical					
points of f when the group is finite, even if the action is not free.					
This investigation has been motivated by the following bifurcation					
problem:					
	$Au = \lambda u$	i			
where A is a variational G-equiva-	riant operator.				

ABSTRACT (continued)

We give an estimate on the number of "branches" bifurcating from an eigenvalue of \mathbf{A}^{\bullet} (0).

